## FRTN10 Multivariable Control, fall 2018

## Administration

Course responsible is Anton Cervin (anton@control.lth.se, 046-222 32 70, M:5142). Course administrator is Mika Nishimura (mika@control.lth.se, 046-222 87 85, M:5141). Their offices are on the 5th floor of the M building.

## Prerequisites

FRT010 Automatic Control, Basic Course or FRTN25 Automatic Process Control is required prior knowledge. It is assumed that you have taken the basic courses in mathematics, including linear algebra and calculus in several variables, and preferably also a course in systems & transforms or similar.

## **Course material**

All course material is available in English. Lecture slides, lecture notes, excercise problems, and laboratory assignments are provided on the **course homepage**:

http://www.control.lth.se/course/FRTN10

Optional reading is provided in Glad & Ljung: *Control Theory: Multivariable and Nonlinear Methods*, Taylor & Francis (available as e-book through Lund University Libraries)

## Lectures

The lectures (30 hours in total) are given by Anton Cervin on Mondays, Tuesdays, and Thursdays. See the LTH schedule generator for details.

## **Exercise sessions**

The exercise sessions (28 hours in total) are supervised by Hamed Sedaghi, Martin Heyden and Martin Morin. They are arranged in two groups (free choice):

Group	Times	Room
1	Wednesdays 10–12, Fridays 10–12	M:M1 or Lab A
2	Wednesdays 13–15, Fridays 13–15	M:M1 or Lab A

The five computer exercises are held in the course lab of Automatic Control LTH, located on the ground floor in the southern part of the M-building. You can also do most of the computer exercises on your own computer if you have Matlab with Control System Toolbox installed.

## Laboratory experiments

The three laboratory sessions (12 hours in total) are mandatory. A link to the booking system (SAM) will be posted on the course homepage. You must sign up before the first session starts. Before each session there are pre-lab assignments that must be completed. No reports are required afterwards.

Lab	Weeks	Booking opens	Room	Responsible	Process
1	38–39	Sep 6	Lab C	Hamed Sedaghi	Flexible linear servo
<b>2</b>	39–40	Sep 17	Lab C	Martin Heyden	Quadruple tank
3	41 - 42	Sep 27	Lab B	Martin Morin	MinSeg

## Exam

The exam is given on Saturday October 27 at 08:00–13:00. Retake exams are offered in April and August, 2019. Lecture slide handouts (with markings/notes) are allowed on the exam. You may also bring *Automatic Control—Collection of Formulae*, standard mathematical tables (TEFYMA), and a pocket calculator.

# Weekly plan, fall 2018

Week	e Date		Content	Glad & Ljung			
36	Sep 3 Sep 4 Sep 5 Sep 6	L1: L2: E1: L3:	Introduction Stability and robustness Control basics Specifications and disturbance models	1.1–1.5 1.6, 2.1–2.5, 3.1, 3.4–3.5 5.1–5.6, 6.1–6.3			
37	Sep 7 Sep 10	E2: <b>L4:</b>	System representations and stability Control synthesis in frequency domain	$6.4-6.6\ 8.1-8.2$			
	Sep 12 Sep 13 Sep 14	E3: <b>L5:</b> E4:	Disturbance models and robustness Case study: DVD player Matlab, loop shaping, preparations for Lab 1	_			
38	Sep 18 Sep 19	<b>L6:</b> E5:	Controllability/observability, multivariable poles/zeros Controllability/observability, poles & zeros,	3.2–3.3, 3.5–3.6			
	Sep 20 Sep 21	<b>L7:</b> E6:	minimal realizations <b>Fundamental limitations</b> Fundamental limitations	7.2–7.9			
38–39	LAB SESSION 1: Loop shaping for a flexible linear servo						
39	Sep 25 Sep 26 Sep 27 Sep 28	<b>L8:</b> E7: <b>L9:</b> E8:	Decentralized control Decentralized control, preparations for Lab 2 Linear-quadratic control Linear-quadratic control	8.3			
39–40	LAB SESSION 2: Decentralized control of quadruple tank						
40	Oct 2 Oct 3 Oct 4 Oct 5	<b>L10:</b> E9: <b>L11:</b> E10:	<b>Kalman filtering</b> Kalman filtering <b>LQG control</b> LQG control, preparations for Lab 3	5.7 9.1–9.4			
41	Oct 8 Oct 10 Oct 11 Oct 12	<b>L12:</b> E11: <b>L13:</b> E12:	Youla parametrization, internal model control Youla parametrization, internal model control Synthesis by convex optimization Synthesis by convex optimization	8.4			
41–42	LAB SESSION 3: LQG control of the MinSeg						
42	Oct 16 Oct 17 Oct 18 Oct 19	<b>L14:</b> E13: <b>L15:</b> E14:	Controller simplification Controller simplification Course review Old exam	3.6			
43	Oct 27		EXAM				