

## Homework assignment 4

Exercises 1 and 2 are Hand-in exercises.

1. Compute the proximal operator to the following functions  $f$ . For each example do the following:
  - (i) Indicate if the proximal operator is separable.
  - (ii) Provide a rough estimate (if possible) of the computational cost of evaluating the proximal operator (or point out the most costly operation).
  - (iii) Consider computing the prox of  $f \circ L$  where  $L$  is an arbitrary linear operator. Estimate if the computational cost of computing this prox is significantly increased compared to computing the prox of  $f$ .
  - (iv) Decide if the function satisfies the properties needed to guarantee convergence using a forward-step (gradient-step) of its gradient. That is, decide if  $f$  differentiable with  $\nabla f$  cocoercive (or equivalently, decide if  $f$  smooth).
  - (v) If a forward-step in (iv) is OK, compare the computational cost of the forward-step and the prox-step (with and without composition).
  - a.  $f(x) = \|x\|_1$ .
  - b.  $f(x) = \|x\|_0$  (counts the number of nonzero elements (nonconvex)).
  - c.  $f(x) = \frac{1}{2}x^T Hx$  where  $H$  is full symmetric and positive semi-definite.
  - d.  $f(x) = \|x\|$ .
  - e.  $f(x) = \frac{1}{2}\|x\|^2$ .
  - f.  $f(x) = \|x\|_1 + \frac{1}{2}\|x\|^2$ .
  - g.  $f(x) = \iota_C(x)$  where  $C \neq \emptyset$  is a general closed and convex set.
  - h.  $f(x) = \iota_V(x)$  where  $V = \{x \mid Lx = b\} \neq \emptyset$ .
  - i.  $f(x) = \iota_B(x)$  where  $B = \{x \mid l \leq x \leq u\} \neq \emptyset$ .

### 2. Moreau's identity and generalizations.

- a. Assume that  $A$  is a maximal monotone operator and that  $\gamma \in (0, \infty)$ . Prove the generalized Moreau identity:

$$J_{\gamma A} + \gamma J_{\gamma^{-1}A^{-1}} \circ (\gamma^{-1}\text{Id}) = \text{Id}.$$

- b. Let  $f$  be proper closed and convex and  $L$  be a linear operator and let  $\gamma \in (0, \infty)$ . Further assume that  $f \circ L$  is proper. Show that if

$$s^* \in \underset{s}{\text{Argmin}} \{g^*(s) + \frac{\gamma}{2}\|L^*s - \gamma^{-1}z\|^2\}$$

exists, then

$$\text{prox}_{\gamma(f \circ L)}(z) = z - \gamma L^* s^*$$

3. Assume that  $\beta \in (0, 1)$  and that  $T$  is  $\frac{1}{\beta}$ -cocoercive. Show that  $T + (1 - \beta)\text{Id}$  is  $\frac{\beta}{2}$ -averaged.
4. Suppose that  $f$  is proper closed and convex.
  - a. Assume that  $f$  is  $\sigma$ -strongly convex with  $\sigma \in (0, \infty)$ . Then the reflected resolvent  $R_f$  is  $\alpha$ -negatively averaged. Provide a value for  $\alpha$ .
  - b. Assume that  $f$  is  $\beta$ -smooth with  $\beta \in (0, \infty)$ . Then the reflected resolvent  $R_f$  is  $\alpha$ -averaged. Provide a value for  $\alpha$ .
5. Consider the problem

$$\text{minimize } \frac{1}{2}\|Ax - b\|^2 + \lambda\|Dx\|_1 \quad (\text{P})$$

where  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ ,  $D \in \mathbb{R}^{p \times n}$ ,  $x \in \mathbb{R}^n$ , and  $\lambda \in (0, \infty)$ . Assume that  $A$  and  $D$  always have full rank. We will consider two different dual problems for (P). The primal problem can be written on the following general form

$$\text{minimize } f(x) + g(Lx).$$

Let  $f(x) = \frac{1}{2}\|Ax - b\|^2$  and  $g_1(x) = \lambda\|Dx\|_1$  to get the first dual problem

$$\text{minimize } f^*(-\mu) + g_1^*(\mu). \quad (\text{D1})$$

Let  $f(x) = \frac{1}{2}\|Ax - b\|^2$ ,  $g_2(y) = \lambda\|y\|_1$ , and  $L = D$  to get the second dual problem

$$\text{minimize } f^*(-L^*\mu) + g_2^*(\mu). \quad (\text{D2})$$

Consider the following cases:

- (i)  $m \geq n$  and  $D = I$
  - (ii)  $m \geq n$  and  $p < n$  and  $D$  general structure
  - (iii)  $m \geq n$  and  $p \geq n$  and  $D$  general structure
  - (iv)  $m < n$  and  $D = I$
  - (v)  $m < n$  and  $p < n$  and  $D$  general structure
  - (vi)  $m < n$  and  $p \geq n$  and  $D$  general structure
- a. For each of these cases, motivate if the problem can be solved by forward-backward splitting applied to (P), (D1), and/or (D2). Also provide bounds on  $\gamma$  in each case and algorithm for which the algorithm is guaranteed to converge.
  - b. For each of these cases, motivate which forward-backward method that gets cheapest iterations. That is, if forward-backward splitting applied to (P), (D1), or (D2) (if applicable) gets the cheapest iteration cost.
  - c. For each problem and (feasible) forward-backward splitting method (that is FB applied to (P), (D1), (D2)), motivate if the convergence is linear or sublinear.
  - d. Implement the algorithms using random  $A$  and  $D$  (where applicable).