

$$1.2.1. \begin{cases} \dot{x} = u \\ x(0) = 1 \end{cases}$$

$$\text{Minimiere } J = \int_0^{\infty} (x^2 + u^2) dt = \int_0^{\infty} (x^2 + \dot{x}^2) dt$$

$$\int_0^T (x(t) + \dot{x}(t))^2 dt = \int_0^T (x^2(t) + \dot{x}^2(t) + 2x(t)\dot{x}(t)) dt = \int_0^T (x^2(t) + \dot{x}^2(t)) dt +$$

$$+ [x^2(t)]_0^T = \int_0^T (x^2(t) + \dot{x}^2(t)) dt + x^2(T) - x^2(0)$$

$$\Rightarrow J = x^2(0) - x^2(\infty) + \int_0^{\infty} (x(t) + \dot{x}(t))^2 dt$$

$$J \text{ beschränkt} \Rightarrow x(\infty) = 0$$

$$\Rightarrow J \leq x^2(0) = 1.$$

$$\left. \begin{array}{l} x(t) + \dot{x}(t) = 0 \\ x(0) = 1 \end{array} \right\} \Rightarrow x(t) = e^{-t}$$

$$J = 1 \Rightarrow \textcircled{1} \text{ oder } \textcircled{2}$$

$$\textcircled{1} \quad \underline{u(t) = \dot{x}(t) = -e^{-t}}$$

$$\textcircled{2} \quad \underline{u(t) = -x(t)}$$

1.2.2. Modell:  $\dot{x} = au$

Verklüft System:  $\dot{x} = u$

$$\begin{aligned} J_n &= \int_0^{\infty} (x'(t) + u^2(t)) dt = \int_0^{\infty} (x'(t) + \frac{1}{a^2} \dot{x}^2(t)) dt = \int_0^{\infty} (x^2 + \frac{1}{a^2} \dot{x}^2 + 2x\dot{x}/a - 2x\dot{x}/a) dt = \\ &= \int_0^{\infty} (x(t) + \frac{1}{a} \dot{x}(t))^2 dt + \frac{1}{a} x(0) - \frac{1}{a} x(\infty) \end{aligned}$$

①  $u(t) = -x(t) \Rightarrow J = 1$

②  $u(t) = -e^{-at}$

$$x(t) = 1 - \int_0^t e^{-as} ds = 1 + \left[ \frac{1}{a} e^{-as} \right]_0^t = 1 + \frac{1}{a} (e^{-at} - 1) = \frac{a-1+e^{-at}}{a}$$

$$\begin{aligned} J &= \int_0^{\infty} (x(t)^2 + u^2(t)) dt = \int_0^{\infty} \left( \frac{(a-1+e^{-at})^2 + e^{-2at}}{a^2} \right) dt = \\ &= \int_0^{\infty} \frac{(a-1)^2 + 2(a-1)e^{-at} + 2e^{-2at}}{a^2} dt = \left[ \frac{(a-1)^2}{a^2} t - \frac{2(a-1)}{a^2} e^{-at} - \frac{e^{-2at}}{a^2} \right]_0^{\infty} \end{aligned}$$

$$J = \lim_{t \rightarrow \infty} \frac{(a-1)^2}{a^2} t + \frac{2(a-1)}{a^2} + \frac{1}{a^2} = \underline{\underline{\infty}}$$

$$1.3.1. \quad x(t) = a \cos t$$

$$\begin{aligned} \underline{x(t+i)} &= a \cos(t+i) = a (\cos t \cos 1 - \sin t \sin 1) = x(t) \cdot \cos 1 - \sin t \sin 1 \\ &= x(t) \cos 1 - \cos(t - \frac{\pi}{2}) \sin 1 = \underline{x(t) \cos 1 - x(t - \frac{\pi}{2}) \sin 1} \end{aligned}$$

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$$x(t_0) = a \cos t_0 \Rightarrow a = \frac{x(t_0)}{\cos t_0}$$

$$\underline{x(t)} = a \cos t = \frac{x(t_0)}{\cos t_0} \cos t$$

1.3.2.

$$\begin{cases} x(t+i) = ax(t) + e(t) \\ \hat{x}(t+i) = ax(t) \end{cases}$$

$$E(x(t+i) - \hat{x}(t+i))^2 = E(ax(t) + e(t) - ax(t))^2 = E(e(t))^2 = \sigma^2$$

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