

correction or better expression

26	↑ 12	6. Prove that	5. Prove that
31	↑ 7	$\int_0^\infty \frac{\sin x}{x} dx = \frac{\pi}{2}$	$\int_0^\infty \frac{\sin x}{x} dx = \frac{\pi}{2}$
47	↑ 10	stochastic differential equation	stochastic difference equation
55	↑ 13	an ordinary stochastic differential	an ordinary differential
105	↑ 5	a weakly stationary stochastic	a second order stochastic
113	↑ 5	increments which has the covariance	increments has the covariance
132	↑ 14	For Re S ≥ 0	For Re S ≥ 0
133	↑ 3	...1 > $\frac{1}{2}(A_k(s) - A_k(-s)) = 0$...1 ≥ $\frac{1}{2}(A_k(s) - A_k(-s)) > 0$
137	↓ 19	$\frac{1}{2\pi i} \int_{-i\infty}^{i\infty} \frac{A_k(s)A_k(-s)}{A_k(s)A_k(-s)} ds =$	$\frac{1}{2\pi i} \int_{-i\infty}^{i\infty} \frac{A_k(s)A_k(-s)}{A_k(s)A_k(-s)} ds =$
138	↓ 4	$a_0^{n-1} 0 a_3^{n-1} 0$ $\vdots \vdots$	$a_1^{n-1} 0 a_3^{n-1} 0$ $\vdots \vdots$
"	↓ 18	$a_{i+1}^k a_i^k$	$a_{i+1}^k - a_k a_{i+2}^k$
"	↓ 19	b_{i+1}^k	$b_{i+1}^k \quad i \text{ even}$

138 $\dagger 21 \quad b_{i+1}^k - \beta_k a_{i+1}^k \quad i \text{ odd}$

143 $\dagger 10 \quad \text{construction } x \text{ will}$

150 $\dagger 8 \quad \text{in Section, we}$

161 $\dagger 18 \quad \text{into (2.1) and}$

" $\dagger 11 \quad -ay(t) + bu(t) + ce(t)$

165 $\dagger 13 \quad e(t), e(t-1), \dots$

173 eq.(4.11) $z^n + a_1 z^{n-1} + \dots + c_n$

216 $\dagger 6 \quad \hat{x}(t+h|t) = x(t)$

220 $\dagger 17 \quad = (2\pi)^{\frac{n}{2}} (\det R_z)^{-\frac{1}{2}} \exp.$

222 $\dagger 3 \quad ||z||^2 = R_x^{-1} R_{xy} R_{yy}^{-1} R_{yx}$

223 $\dagger 12 \quad \text{Theorem 3.2}$

230 Fig. 7.2 the signal given

b_{i+1}^k - β_k a_{i+1}^k i even

construction \hat{x} will

in Section 4, we

into (2.2) and

-ay(t) + u(t) + ce(t)

e(t), e(t-1), ...

$z^n + c_1 z^{n-1} + \dots + c_n$

$x(t+h|t) = e^{-\frac{1}{2}rh} x(t).$

$= (2\pi)^{\frac{n}{2}} (\det R_z)^{-\frac{1}{2}} \exp.$

$||z||^2 = R_x^{-1} R_{xy} R_{yy}^{-1} R_{yx}$

Theorem 3.3

the system given

232 4 3 $\{[\Phi - K(t)\Theta]P(t)\Theta^T + K(t)R_2\} = 0$

246 4 10 $-(Q-P)CR_2^{-1}C^TP - \dots$

246 4 13 Eg (6.20)

257 4 14 Lemma 3.1

262 4 2~3 conditional expectations given y , commute

272 4 18 $-L^T(Q_2 + L^T S(t+1)L)L]\hat{x}$

" 4 3 $L(t)Q_2L^T(t) + Q_1$
 + $u^T(s)Q_0u(s)]$

273 4 1 $\hat{x}(t) = \hat{x}(t) - x(t)$

276 4 3 comparisons

279 4 3 Excercise 4.3 of chapter 7

282 4 16 $\{[\Phi - K(t)\Theta]P(t)\Theta^T - K(t)R_2\} = 0$

-(Q-P)C $R_2^{-1}C^TP - \dots$

Eg (6.21)

Lemma 3.2

conditional expectations with respect to distribution
of y , commute

$-L^T(Q_2 + L^T S(t+1)L)L]\hat{x}$

$L^T(t)Q_2L(t) + Q_1$
+ $u^T(s)Q_0u(s)]$

$\hat{x}(t) = x(t) - \hat{x}(t)$

comparison

Excercise 3 in Section 4 of chapter 7